What drives transient behaviour in complex systems?

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October 4, 2018

Random Matrices, Integrability and Complex Systems

Yad Hashmona based on Phys. Rev. E 96, 022316

- Motivation(s)
- May-Wigner and beyond
- Generators of transient behaviour

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- Choose a dynamical complex system Description: $\frac{dx_i}{dt} = f_i(x_1...x_N), \quad i = 1...N$ Examples
 - 1 Lotka-Volterra $f_i = x_i(1 \sum_j \alpha_{ij}x_j)$

2 deep learning
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x(t)

• Eigenvalues of M – late time analysis

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where $|y(t)|^2 = \sum_i y_i^2$ is the norm.

• Two indicators amplification and reactivity:

$$A = \max_{t \ge 0} \frac{|y(t)|^2}{|y_0|^2}, \qquad R = \frac{1}{|y_0|^2} \lim_{t \to 0} \frac{d|y(t)|^2}{dt},$$

where y_0 is the initial condition.

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• we have
$$A = \max_{t \geq 0} \left(1 + Rt + \mathcal{O}(t^2) \right)$$

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- Neubert & Caswell 1997 rainforest compartment model
- Consider the following mass-energy flow diagram:



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• the matrix M:

TABLE 2. Transfer matrix for elemental dynamics in a Panamanian tropical forest (cf. McGinnis et al. 1969).

Compartment' and number		1	2	3	4	5	6	7	8	9
Leaves	1	-1.5622†	0.6685							
Stems	2		-0.7119			2.5632				
Litter	3	1.4627	0.0364	-6.4091			1.1446		55.8201	17.2972
Soil	4				-0.0222			315.9443		
Roots	5				0.0201	-2.5632				
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flowers	6		0.0070				-2.0348			
Detritivores	7			6.4091				-315.9443		
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• all eigenvalues of *M* are negative – stable!

• (late time behaviour) Largest eigenvalue of M: -0.002 yr^{-1}

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• (Lord May 1973) Consider a model:

$$\frac{dy_i}{dt} = \sum_{j=1}^N M_{ij} y_j,$$

• *M* will be of size $N \times N$:

$$M = -\mu 1_N + X$$

where $\mu > 0$ (what is it?) and X is random drawn from:

$$P(X)[dX] \sim \exp\left(-\frac{N}{2\sigma^2} \operatorname{Tr} X^{\mathsf{T}} X\right) [dX],$$

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• Late time behaviour – eigenvalues of *M*. Asymptotic $(N \to \infty)$ density:

$$\rho_M(x,y) = \frac{1}{\pi\sigma^2}\theta\left(\sigma^2 - (x+\mu)^2 - y^2\right),$$

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- Vary μ (or vary σ)
- System is stable if $\mu < \mu_s$ and unstable when $\mu > \mu_s$ for $\mu_s = \sigma$. Phase space is one-dimensional:



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- Treating initial conditions:
 - **1** averaged over $O_{av} = \langle O(y_0) \rangle_{y_0} = \int [dy_0]_\beta p_0(y_0) O(y_0)$
 - 2 maximized $O_{\max} = \max_{y_0} O_{y_0}$

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- We compute it easily:

$$R_{\max} = \max_{y_0} \frac{\langle y_0 | (M^T + M) | y_0 \rangle}{\langle y_0 | y_0 \rangle} = \lambda_{\max} \left(M^T + M \right).$$

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• In the asymptotic $N \to \infty$ limit:

$$\lim_{N \to \infty} \langle R_{\max} \rangle_{X} = -2\mu + 2\mu_{T}, \qquad \mu_{T} = \sqrt{2}\sigma$$

which is found by using the Wigner's semicirlce law for the eigenvalues of $M^T + M$.

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- Voilà, new regime!
- But... We see that $\overline{R_{av}} = -2\mu < 0$. What is then its nature?

• Inspect the distribution of reactivity

$$g(r) = \delta(r - R(y_0))$$

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• Compute two variants

$$\begin{array}{l} \bullet \quad \overline{g_{\mathsf{av}}}(r) = \langle g(r) \rangle_{X,y_{\mathsf{0}}} \\ \bullet \quad \overline{g_{\mathsf{max}}}(r) = \left\langle \max_{y_{\mathsf{0}}} g(r) \right\rangle_{X} \end{array}$$

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• The extreme variant is the GOE Tracy-Widom distribution

$$\overline{g_{\max}}(r) = \left\langle \delta\left(r + 2\mu - \lambda_{\max}(X^T + X)\right) \right\rangle_{X} = \frac{d}{dr} F_{N,\beta=1} \left(\frac{\sqrt{N}}{\sigma} \left(\mu + \frac{r}{2}\right) \right)_{X=0}$$

• The abundance of transient trajectories:

$$\overline{N_{\max}} = \int_0^\infty \overline{g_{\max}}(r) dr, \quad \overline{N_{av}} = \int_0^\infty \overline{g_{av}}(r) dr.$$
$$\overline{N_{\max}}(\mu) = 1 - F_{N,\beta=1}\left(\frac{\sqrt{N}\mu}{\sigma}\right), \overline{N_{av}}(\mu) = \frac{1}{2} \operatorname{erfc}\left(\sqrt{N}\frac{\mu}{\mu_T}\right).$$

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 transient trajectories are (potentially) present in the whole transient regime μ ∈ (μ_S, μ_T) as shown by the behaviour of M_{max}, they are otherwise uncommon as dictated by M_{av} → (E) (E) (E) (E) (E)

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• Go back to reactivity *R* and compute the *X* average as decomposed into two parts

$$\langle R \rangle_{X} = -2\mu + \frac{1}{\langle y_{0} | y_{0} \rangle} \left(\left\langle y_{0} | \left\langle Z^{T} + Z \right\rangle_{X} | y_{0} \right\rangle + \left\langle y_{0} | \left\langle T^{T} + T \right\rangle_{X} | y_{0} \right\rangle \right)$$

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- In May-Wigner model, both terms vanish.
- Introduce a modification of the model fix T and leave the Z unchanged so that only one vanishes.

• Propose a fixed T_0 model:

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- T₀ resembles an *external field*:

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• ...or a (not so distant) echo of eigenvectors

• Phase space is now two-dimensional with proper transient regime:



Recap:

- Transient behaviour is an early time phenomenon abundant in real-life systems
- May-Wigner model contains a regime of parameters where transient dynamics is present although rare
- Transient trajectories are generated by eigenvector degrees of freedom

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- Transient behaviour is an early time phenomenon abundant in real-life systems
- May-Wigner model contains a regime of parameters where transient dynamics is present although rare
- Transient trajectories are generated by eigenvector degrees of freedom Future:

- Reactivity is not an exact measure of transient behaviour
- What about *t*_{max}? or amplification?
- Statistics of the norm $|y(t)|^2$ (variance and beyond)
- Echoes of transient behaviour in the chaotic phase