# What drives transient behaviour in complex systems? 

Jacek Grela<br>Queen Mary University of London

October 4, 2018

Random Matrices, Integrability and Complex Systems
Yad Hashmona
based on Phys. Rev. E 96, 022316

## Outline

- Motivation(s)
- May-Wigner and beyond
- Generators of transient behaviour


## Motivation

- Choose a dynamical complex system Description: $\frac{d x_{i}}{d t}=f_{i}\left(x_{1} \ldots x_{N}\right), \quad i=1 \ldots N$ Examples
(1) Lotka-Volterra $f_{i}=x_{i}\left(1-\sum_{j} \alpha_{i j} x_{j}\right)$
(2) deep learning $f_{i}=\tanh \left(\sum_{j} C_{i j} x_{j}\right)$


## Motivation

- Choose a dynamical complex system Description: $\frac{d x_{i}}{d t}=f_{i}\left(x_{1} \ldots x_{N}\right), \quad i=1 \ldots N$ Examples
(1) Lotka-Volterra $f_{i}=x_{i}\left(1-\sum_{j} \alpha_{i j} x_{j}\right)$
(2) deep learning $f_{i}=\tanh \left(\sum_{j} C_{i j} x_{j}\right)$
- Rich dynamics - fixed points, limit cycles and strange attractors


## Motivation

- Choose a dynamical complex system Description: $\frac{d x_{i}}{d t}=f_{i}\left(x_{1} \ldots x_{N}\right), \quad i=1 \ldots N$ Examples
(1) Lotka-Volterra $f_{i}=x_{i}\left(1-\sum_{j} \alpha_{i j} x_{j}\right)$
(2) deep learning $f_{i}=\tanh \left(\sum_{j} C_{i j} x_{j}\right)$
- Rich dynamics - fixed points, limit cycles and strange attractors
- Simplest case - stability analysis $x_{i}=x_{i}^{*}+y_{i}$ for $f_{i}\left(x^{*}\right)=0$


## Motivation

- Choose a dynamical complex system

Description: $\frac{d x_{i}}{d t}=f_{i}\left(x_{1} \ldots x_{N}\right), \quad i=1 \ldots N$ Examples
(1) Lotka-Volterra $f_{i}=x_{i}\left(1-\sum_{j} \alpha_{i j} x_{j}\right)$
(2) deep learning $f_{i}=\tanh \left(\sum_{j} C_{i j} x_{j}\right)$

- Rich dynamics - fixed points, limit cycles and strange attractors
- Simplest case - stability analysis $x_{i}=x_{i}^{*}+y_{i}$ for $f_{i}\left(x^{*}\right)=0$ Linear equation for deviations:

$$
\frac{d y_{i}}{d t}=\sum_{j=1}^{N} M_{i j} y_{j}, \quad M_{i j}=\partial_{x_{j}} f_{i}(x)_{\mid x=x^{*}}
$$

## Motivation

- Choose a dynamical complex system Description: $\frac{d x_{i}}{d t}=f_{i}\left(x_{1} \ldots x_{N}\right), \quad i=1 \ldots N$ Examples
(1) Lotka-Volterra $f_{i}=x_{i}\left(1-\sum_{j} \alpha_{i j} x_{j}\right)$
(2) deep learning $f_{i}=\tanh \left(\sum_{j} C_{i j} x_{j}\right)$
- Rich dynamics - fixed points, limit cycles and strange attractors
- Simplest case - stability analysis $x_{i}=x_{i}^{*}+y_{i}$ for $f_{i}\left(x^{*}\right)=0$ Linear equation for deviations:

$$
\frac{d y_{i}}{d t}=\sum_{j=1}^{N} M_{i j} y_{j}, \quad M_{i j}=\partial_{x_{j}} f_{i}(x)_{\mid x=x^{*}}
$$

- Inspect eigenvalues of $M$


## Motivation

- Choose a dynamical complex system

Description: $\frac{d x_{i}}{d t}=f_{i}\left(x_{1} \ldots x_{N}\right), \quad i=1 \ldots N$ Examples
(1) Lotka-Volterra $f_{i}=x_{i}\left(1-\sum_{j} \alpha_{i j} x_{j}\right)$
(2) deep learning $f_{i}=\tanh \left(\sum_{j} C_{i j} x_{j}\right)$

- Rich dynamics - fixed points, limit cycles and strange attractors
- Simplest case - stability analysis $x_{i}=x_{i}^{*}+y_{i}$ for $f_{i}\left(x^{*}\right)=0$ Linear equation for deviations:

$$
\frac{d y_{i}}{d t}=\sum_{j=1}^{N} M_{i j} y_{j}, \quad M_{i j}=\partial_{x_{j}} f_{i}(x)_{\mid x=x^{*}}
$$

- Inspect eigenvalues of $M$



## Motivation

- Eigenvalues of $M$ - late time analysis


## Motivation

- Eigenvalues of $M$ - late time analysis
- What about intermediate or early times? Hard in general...


## Motivation

- Eigenvalues of $M$ - late time analysis
- What about intermediate or early times? Hard in general...
- A tangible feature - transient (growth) behaviour

where $|y(t)|^{2}=\sum_{i} y_{i}^{2}$ is the norm.


## Motivation

- Eigenvalues of $M$ - late time analysis
- What about intermediate or early times? Hard in general...
- A tangible feature - transient (growth) behaviour

where $|y(t)|^{2}=\sum_{i} y_{i}^{2}$ is the norm.
- Two indicators amplification and reactivity:

$$
A=\max _{t \geq 0} \frac{|y(t)|^{2}}{\left|y_{0}\right|^{2}}, \quad R=\frac{1}{\left|y_{0}\right|^{2}} \lim _{t \rightarrow 0} \frac{d|y(t)|^{2}}{d t}
$$

where $y_{0}$ is the initial condition.

## Motivation

- For a linear model the solution (bra-ket notation):

$$
|y(t)\rangle=e^{M t}\left|y_{0}\right\rangle,
$$

## Motivation

- For a linear model the solution (bra-ket notation):

$$
|y(t)\rangle=e^{M t}\left|y_{0}\right\rangle,
$$

- The norm is

$$
\langle y(t) \mid y(t)\rangle=\left\langle y_{0}\right| e^{M^{T} t} e^{M t}\left|y_{0}\right\rangle
$$

## Motivation

- For a linear model the solution (bra-ket notation):

$$
|y(t)\rangle=e^{M t}\left|y_{0}\right\rangle,
$$

- The norm is

$$
\langle y(t) \mid y(t)\rangle=\left\langle y_{0}\right| e^{M^{\top} t} e^{M t}\left|y_{0}\right\rangle
$$

- and so the reactivity

$$
R=\frac{\left\langle y_{0}\right|\left(M^{T}+M\right)\left|y_{0}\right\rangle}{\left\langle y_{0} \mid y_{0}\right\rangle}
$$

## Motivation

- For a linear model the solution (bra-ket notation):

$$
|y(t)\rangle=e^{M t}\left|y_{0}\right\rangle,
$$

- The norm is

$$
\langle y(t) \mid y(t)\rangle=\left\langle y_{0}\right| e^{M^{\top} t} e^{M t}\left|y_{0}\right\rangle
$$

- and so the reactivity

$$
R=\frac{\left\langle y_{0}\right|\left(M^{T}+M\right)\left|y_{0}\right\rangle}{\left\langle y_{0} \mid y_{0}\right\rangle}
$$

- we have $A=\max _{t \geq 0}\left(1+R t+\mathcal{O}\left(t^{2}\right)\right)$.


## Motivation

- When does it show up? $M$ must be asymmetric. Not concrete enough!


## Motivation

- When does it show up? $M$ must be asymmetric. Not concrete enough!
- Does it matter? It does, at least for fluids, brains and ecosystems


## Motivation

- When does it show up? $M$ must be asymmetric. Not concrete enough!
- Does it matter? It does, at least for fluids, brains and ecosystems
- Neubert \& Caswell 1997 - rainforest compartment model


## Motivation

- When does it show up? $M$ must be asymmetric. Not concrete enough!
- Does it matter? It does, at least for fluids, brains and ecosystems
- Neubert \& Caswell 1997 - rainforest compartment model
- Consider the following mass-energy flow diagram:



## Motivation

- The model is of the same form:

$$
\frac{d y_{i}}{d t}=\sum_{j=1}^{9} M_{i j} y_{j}
$$

## Motivation

- The model is of the same form:

$$
\frac{d y_{i}}{d t}=\sum_{j=1}^{9} M_{i j} y_{j}
$$

- the matrix $M$ :

Table 2. Transfer matrix for elemental dynamics in a Panamanian tropical forest (cf. McGinnis et al. 1969).

| Compartmen and number |  | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Leaves | 1 | $-1.5622 \dagger$ | 0.6685 |  |  |  |  |  |  |  |
| Stems | 2 |  | -0.7119 |  |  | 2.5632 |  |  |  |  |
| Litter | 3 | 1.4627 | 0.0364 | -6.4091 |  |  | 1.1446 |  | 55.8201 | 17.2972 |
| Soil | 4 |  |  |  | -0.0222 |  |  | 315.9443 |  |  |
| Roots | 5 |  |  |  | 0.0201 | -2.5632 |  |  |  |  |
| Fruits and flowers | 6 |  | 0.0070 |  |  |  | -2.0348 |  |  |  |
| Detritivores | 7 |  |  | 6.4091 |  |  |  | -315.9443 |  |  |
| Herbivores | 8 | 0.0995 |  |  |  |  | 0.8902 |  | -62.6458 |  |
| Carnivores | 9 |  |  |  |  |  |  |  | 6.8257 | -17.2972 |

[^0]
## Motivation

- The model is of the same form:

$$
\frac{d y_{i}}{d t}=\sum_{j=1}^{9} M_{i j} y_{j}
$$

- the matrix $M$ :

Table 2. Transfer matrix for elemental dynamics in a Panamanian tropical forest (cf. McGinnis et al. 1969).

| Compartme and numbe |  | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Leaves | 1 | $-1.5622 \dagger$ | 0.6685 |  |  |  |  |  |  |  |
| Stems | 2 |  | -0.7119 |  |  | 2.5632 |  |  |  |  |
| Litter | 3 | 1.4627 | 0.0364 | -6.4091 |  |  | 1.1446 |  | 55.8201 | 17.2972 |
| Soil | 4 |  |  |  | -0.0222 |  |  | 315.9443 |  |  |
| Roots | 5 |  |  |  | 0.0201 | -2.5632 |  |  |  |  |
| Fruits and flowers | 6 |  | 0.0070 |  |  |  | -2.0348 |  |  |  |
| Detritivores | 7 |  |  | 6.4091 |  |  |  | -315.9443 |  |  |
| Herbivores | 8 | 0.0995 |  |  |  |  | 0.8902 |  | -62.6458 |  |
| Carnivores | 9 |  |  |  |  |  |  |  | 6.8257 | -17.2972 |

$\dagger$ All entries are in units of $\mathrm{yr}^{-1}$.

- all eigenvalues of $M$ are negative - stable!


## Motivation

- (late time behaviour) Largest eigenvalue of $M$ : $-0.002 \mathrm{yr}^{-1}$


## Motivation

- (late time behaviour) Largest eigenvalue of $M$ : $-0.002 \mathrm{yr}^{-1}$
- (early time behaviour)(maximal) reactivity $\max R=65.4 \mathrm{yr}^{-1}$ yo


## Motivation

- (late time behaviour) Largest eigenvalue of $M$ : $-0.002 \mathrm{yr}^{-1}$
- (early time behaviour)(maximal) reactivity $\max R=65.4 \mathrm{yr}^{-1}$
- very different timescales!


## Motivation

- (late time behaviour) Largest eigenvalue of $M$ : $-0.002 \mathrm{yr}^{-1}$
- (early time behaviour)(maximal) reactivity $\max R=65.4 \mathrm{yr}^{-1}$
- very different timescales!

Plot of $\max _{y_{0}} \frac{|y(t)|^{2}}{\left|y_{0}\right|^{2}}$ in log-plot:

a giant amplification

## May-Wigner model

- (Lord May 1973) Consider a model:

$$
\frac{d y_{i}}{d t}=\sum_{j=1}^{N} M_{i j} y_{j}
$$

- $M$ will be of size $N \times N$ :

$$
M=-\mu 1_{N}+X
$$

where $\mu>0$ (what is it?) and $X$ is random drawn from:

$$
P(X)[d X] \sim \exp \left(-\frac{N}{2 \sigma^{2}} \operatorname{Tr} X^{T} X\right)[d X]
$$

## May-Wigner model

- Late time behaviour - eigenvalues of $M$. Asymptotic $(N \rightarrow \infty)$ density:

$$
\rho_{M}(x, y)=\frac{1}{\pi \sigma^{2}} \theta\left(\sigma^{2}-(x+\mu)^{2}-y^{2}\right),
$$

or the circular law (only translated)

## May-Wigner model

- Late time behaviour - eigenvalues of $M$. Asymptotic $(N \rightarrow \infty)$ density:

$$
\rho_{M}(x, y)=\frac{1}{\pi \sigma^{2}} \theta\left(\sigma^{2}-(x+\mu)^{2}-y^{2}\right),
$$

or the circular law (only translated)

- Vary $\mu$ (or vary $\sigma$ )


## May-Wigner model

- Late time behaviour - eigenvalues of $M$. Asymptotic $(N \rightarrow \infty)$ density:

$$
\rho_{M}(x, y)=\frac{1}{\pi \sigma^{2}} \theta\left(\sigma^{2}-(x+\mu)^{2}-y^{2}\right),
$$

or the circular law (only translated)

- Vary $\mu$ (or vary $\sigma$ )
- System is stable if $\mu<\mu_{s}$ and unstable when $\mu>\mu_{s}$ for $\mu_{s}=\sigma$. Phase space is one-dimensional:



## Beyond May-Wigner model

- How to include transients? Find a proper observable.


## Beyond May-Wigner model

- How to include transients? Find a proper observable.
- Treating randomness by averaging over $X: \bar{O}=\int[d X] P(X) O(X)$.


## Beyond May-Wigner model

- How to include transients? Find a proper observable.
- Treating randomness by averaging over $X: \bar{O}=\int[d X] P(X) O(X)$.
- Treating initial conditions:
(1) averaged over $O_{\mathrm{av}}=\left\langle O\left(y_{0}\right)\right\rangle_{y_{0}}=\int\left[d y_{0}\right]_{\beta} p_{0}\left(y_{0}\right) O\left(y_{0}\right)$
(2) maximized $O_{\max }=\max _{y_{0}} O$,


## Beyond May-Wigner model

- How to include transients? Find a proper observable.
- Treating randomness by averaging over $X: \bar{O}=\int[d X] P(X) O(X)$.
- Treating initial conditions:
(1) averaged over $O_{\mathrm{av}}=\left\langle O\left(y_{0}\right)\right\rangle_{y_{0}}=\int\left[d y_{0}\right]_{\beta} p_{0}\left(y_{0}\right) O\left(y_{0}\right)$
(2) maximized $O_{\text {max }}=\max _{y_{0}} O$,
- Measuring transient behaviour - study the sign of reactivity $R \ldots$


## Beyond May-Wigner model

- How to include transients? Find a proper observable.
- Treating randomness by averaging over $X: \bar{O}=\int[d X] P(X) O(X)$.
- Treating initial conditions:
(1) averaged over $O_{\mathrm{av}}=\left\langle O\left(y_{0}\right)\right\rangle_{y_{0}}=\int\left[d y_{0}\right]_{\beta} p_{0}\left(y_{0}\right) O\left(y_{0}\right)$
(2) maximized $O_{\text {max }}=\max _{y_{0}} O$,
- Measuring transient behaviour - study the sign of reactivity $R \ldots$
- ...or $\overline{R_{\max }}$ - the $X$-averaged worst case scenario.


## Beyond May-Wigner model

- How to include transients? Find a proper observable.
- Treating randomness by averaging over $X: \bar{O}=\int[d X] P(X) O(X)$.
- Treating initial conditions:
(1) averaged over $O_{\mathrm{av}}=\left\langle O\left(y_{0}\right)\right\rangle_{y_{0}}=\int\left[d y_{0}\right]_{\beta} p_{0}\left(y_{0}\right) O\left(y_{0}\right)$
(2) maximized $O_{\text {max }}=\max _{y_{0}} O$,
- Measuring transient behaviour - study the sign of reactivity $R \ldots$
- ...or $\overline{R_{\max }}$ - the $X$-averaged worst case scenario.
- We compute it easily:

$$
R_{\max }=\max _{y_{0}} \frac{\left\langle y_{0}\right|\left(M^{T}+M\right)\left|y_{0}\right\rangle}{\left\langle y_{0} \mid y_{0}\right\rangle}=\lambda_{\max }\left(M^{T}+M\right) .
$$

## Beyond May-Wigner model

- How to include transients? Find a proper observable.
- Treating randomness by averaging over $X: \bar{O}=\int[d X] P(X) O(X)$.
- Treating initial conditions:
(1) averaged over $O_{\mathrm{av}}=\left\langle O\left(y_{0}\right)\right\rangle_{y_{0}}=\int\left[d y_{0}\right]_{\beta} p_{0}\left(y_{0}\right) O\left(y_{0}\right)$
(2) maximized $O_{\max }=\max _{y_{0}} O$,
- Measuring transient behaviour - study the sign of reactivity $R \ldots$
- ...or $\overline{R_{\max }}$ - the $X$-averaged worst case scenario.
- We compute it easily:

$$
R_{\max }=\max _{y_{0}} \frac{\left\langle y_{0}\right|\left(M^{T}+M\right)\left|y_{0}\right\rangle}{\left\langle y_{0} \mid y_{0}\right\rangle}=\lambda_{\max }\left(M^{T}+M\right) .
$$

- In the asymptotic $N \rightarrow \infty$ limit:

$$
\lim _{N \rightarrow \infty}\left\langle R_{\max }\right\rangle_{X}=-2 \mu+2 \mu_{T}, \quad \mu_{T}=\sqrt{2} \sigma
$$

which is found by using the Wigner's semicirlce law for the eigenvalues of $M^{T}+M$.

## Beyond May-Wigner model

- stable transient if $\overline{R_{\max }}>0$ and stable non-transient $\overline{R_{\max }}<0$


## Beyond May-Wigner model

- stable transient if $\overline{R_{\max }}>0$ and stable non-transient $\overline{R_{\max }}<0$
- A new window opens in the phase space of the model:



## Beyond May-Wigner model

- stable transient if $\overline{R_{\max }}>0$ and stable non-transient $\overline{R_{\max }}<0$
- A new window opens in the phase space of the model:

- Voilà, new regime!


## Beyond May-Wigner model

- stable transient if $\overline{R_{\max }}>0$ and stable non-transient $\overline{R_{\max }}<0$
- A new window opens in the phase space of the model:

- Voilà, new regime!
- But... We see that $\overline{R_{\mathrm{av}}}=-2 \mu<0$. What is then its nature?


## More on stable transient regime

- Inspect the distribution of reactivity

$$
g(r)=\delta\left(r-R\left(y_{0}\right)\right)
$$

## More on stable transient regime

- Inspect the distribution of reactivity

$$
g(r)=\delta\left(r-R\left(y_{0}\right)\right)
$$

- Compute two variants
(1) $\overline{g_{\mathrm{av}}}(r)=\langle g(r)\rangle_{X, y_{0}}$
(2) $\overline{g_{\max }}(r)=\left\langle\max _{y_{0}} g(r)\right\rangle_{X}$


## More on stable transient regime

- Inspect the distribution of reactivity

$$
g(r)=\delta\left(r-R\left(y_{0}\right)\right)
$$

- Compute two variants
(1) $\overline{g_{\mathrm{av}}}(r)=\langle g(r)\rangle_{X, y_{0}}$
(2) $\overline{g_{\max }}(r)=\left\langle\max _{y_{0}} g(r)\right\rangle_{x}$
- In one case $y_{0}$ is particular, in the other it is typical


## More on stable transient regime

- Inspect the distribution of reactivity

$$
g(r)=\delta\left(r-R\left(y_{0}\right)\right)
$$

- Compute two variants
(1) $\overline{g_{\mathrm{av}}}(r)=\langle g(r)\rangle_{X, y_{0}}$
(2) $\overline{g_{\max }}(r)=\left\langle\max _{y_{0}} g(r)\right\rangle_{x}$
- In one case $y_{0}$ is particular, in the other it is typical
- Averaged variant is found by completing the square

$$
\overline{g_{\mathrm{av}}}(r)=\frac{1}{\sqrt{2 \pi \sigma_{R}^{2}}} e^{-\frac{(r+2 \mu)^{2}}{2 \sigma_{R}^{2}}}, \quad \sigma_{R}^{2}=4 \sigma^{2} / N
$$

## More on stable transient regime

- Inspect the distribution of reactivity

$$
g(r)=\delta\left(r-R\left(y_{0}\right)\right)
$$

- Compute two variants
(1) $\overline{g_{\mathrm{av}}}(r)=\langle g(r)\rangle_{X, y_{0}}$
(2) $\overline{g_{\max }}(r)=\left\langle\max _{y_{0}} g(r)\right\rangle_{x}$
- In one case $y_{0}$ is particular, in the other it is typical
- Averaged variant is found by completing the square

$$
\overline{g_{\mathrm{av}}}(r)=\frac{1}{\sqrt{2 \pi \sigma_{R}^{2}}} e^{-\frac{(r+2 \mu)^{2}}{2 \sigma_{R}^{2}}}, \quad \sigma_{R}^{2}=4 \sigma^{2} / N
$$

- The extreme variant is the GOE Tracy-Widom distribution

$$
\overline{g_{\max }}(r)=\left\langle\delta\left(r+2 \mu-\lambda_{\max }\left(X^{T}+X\right)\right)\right\rangle_{X}=\frac{d}{d r} F_{N, \beta=1}\left(\frac{\sqrt{N}}{\sigma}\left(\mu+\frac{r}{2}\right)\right.
$$

- The abundance of transient trajectories:

$$
\begin{gathered}
\overline{N_{\max }}=\int_{0}^{\infty} \overline{g_{\max }}(r) d r, \quad \overline{N_{\mathrm{av}}}=\int_{0}^{\infty} \overline{g_{\mathrm{av}}}(r) d r . \\
\overline{N_{\max }}(\mu)=1-F_{N, \beta=1}\left(\frac{\sqrt{N} \mu}{\sigma}\right), \overline{N_{\mathrm{av}}}(\mu)=\frac{1}{2} \operatorname{erfc}\left(\sqrt{N} \frac{\mu}{\mu_{T}}\right) .
\end{gathered}
$$

- The abundance of transient trajectories:

$$
\begin{gathered}
\overline{N_{\max }}=\int_{0}^{\infty} \overline{g_{\max }}(r) d r, \quad \overline{N_{\mathrm{av}}}=\int_{0}^{\infty} \overline{g_{\mathrm{av}}}(r) d r . \\
\overline{N_{\max }}(\mu)=1-F_{N, \beta=1}\left(\frac{\sqrt{N} \mu}{\sigma}\right), \overline{N_{\mathrm{av}}}(\mu)=\frac{1}{2} \operatorname{erfc}\left(\sqrt{N} \frac{\mu}{\mu_{T}}\right) .
\end{gathered}
$$

- The abundance of transient trajectories:

$$
\begin{aligned}
& \overline{N_{\max }}=\int_{0}^{\infty} \overline{g_{\max }}(r) d r, \quad \overline{N_{\mathrm{av}}}=\int_{0}^{\infty} \overline{g_{\mathrm{av}}}(r) d r . \\
& \overline{N_{\max }}(\mu)=1-F_{N, \beta=1}\left(\frac{\sqrt{N} \mu}{\sigma}\right), \overline{N_{\mathrm{av}}}(\mu)=\frac{1}{2} \operatorname{erfc}\left(\sqrt{N} \frac{\mu}{\mu_{T}}\right) .
\end{aligned}
$$

- transient trajectories are (potentially) present in the whole transient regime $\mu \in\left(\mu_{S}, \mu_{T}\right)$ as shown by the behaviour of $\overline{N_{\max }}$, they are otherwise uncommon as dictated by $\overline{N_{\mathrm{av}}}$.


## Transient behaviour generators

- What determines transient behaviour? (extended) May-Wigner model does hint at its source.


## Transient behaviour generators

- What determines transient behaviour? (extended) May-Wigner model does hint at its source.
- To understand, consider Schur decomposition:

$$
X=O(Z+T) O^{T}
$$

where $T$ is block-upper triangular (eigenvectors), $Z$ block-diagonal (eigenvalues) and $O$ orthogonal.

## Transient behaviour generators

- What determines transient behaviour? (extended) May-Wigner model does hint at its source.
- To understand, consider Schur decomposition:

$$
X=O(Z+T) O^{T}
$$

where $T$ is block-upper triangular (eigenvectors), $Z$ block-diagonal (eigenvalues) and $O$ orthogonal.

- Go back to reactivity $R$ and compute the $X$ average as decomposed into two parts

$$
\begin{aligned}
\langle R\rangle_{X}=-2 \mu+\frac{1}{\left\langle y_{0} \mid y_{0}\right\rangle} & \left(\left\langle y_{0}\right|\left\langle z^{T}+z\right\rangle_{x}\left|y_{0}\right\rangle+\right. \\
& \left.+\left\langle y_{0}\right|\left\langle T^{T}+T\right\rangle_{x}\left|y_{0}\right\rangle\right)
\end{aligned}
$$

## Transient behaviour generators

- What determines transient behaviour? (extended) May-Wigner model does hint at its source.
- To understand, consider Schur decomposition:

$$
X=O(Z+T) O^{T}
$$

where $T$ is block-upper triangular (eigenvectors), $Z$ block-diagonal (eigenvalues) and $O$ orthogonal.

- Go back to reactivity $R$ and compute the $X$ average as decomposed into two parts

$$
\begin{aligned}
\langle R\rangle_{X}=-2 \mu+\frac{1}{\left\langle y_{0} \mid y_{0}\right\rangle} & \left(\left\langle y_{0}\right|\left\langle z^{T}+z\right\rangle_{x}\left|y_{0}\right\rangle+\right. \\
& \left.+\left\langle y_{0}\right|\left\langle T^{T}+T\right\rangle_{x}\left|y_{0}\right\rangle\right)
\end{aligned}
$$

- In May-Wigner model, both terms vanish.


## Transient behaviour generators

- What determines transient behaviour? (extended) May-Wigner model does hint at its source.
- To understand, consider Schur decomposition:

$$
X=O(Z+T) O^{T}
$$

where $T$ is block-upper triangular (eigenvectors), $Z$ block-diagonal (eigenvalues) and $O$ orthogonal.

- Go back to reactivity $R$ and compute the $X$ average as decomposed into two parts

$$
\begin{aligned}
\langle R\rangle_{X}=-2 \mu+\frac{1}{\left\langle y_{0} \mid y_{0}\right\rangle} & \left(\left\langle y_{0}\right|\left\langle z^{T}+z\right\rangle_{x}\left|y_{0}\right\rangle+\right. \\
& \left.+\left\langle y_{0}\right|\left\langle T^{T}+T\right\rangle_{x}\left|y_{0}\right\rangle\right)
\end{aligned}
$$

- In May-Wigner model, both terms vanish.
- Introduce a modification of the model - fix $T$ and leave the $Z$ unchanged so that only one vanishes.


## Transient behaviour generators

- Propose a fixed $T_{0}$ model:

$$
\tilde{P}\left(X ; T_{0}\right)[d X] \sim \delta\left(T-T_{0}\right) P(X)[d X],
$$

## Transient behaviour generators

- Propose a fixed $T_{0}$ model:

$$
\tilde{P}\left(X ; T_{0}\right)[d X] \sim \delta\left(T-T_{0}\right) P(X)[d X]
$$

- Seems artificial but has two properties:
(1) Does not spoil stability (eigenvalues stay in place)
(2) Does modify reactivity (transient regime!)


## Transient behaviour generators

- Propose a fixed $T_{0}$ model:

$$
\tilde{P}\left(X ; T_{0}\right)[d X] \sim \delta\left(T-T_{0}\right) P(X)[d X]
$$

- Seems artificial but has two properties:
(1) Does not spoil stability (eigenvalues stay in place)
(2) Does modify reactivity (transient regime!)
- $T_{0}$ resembles an external field:

$$
\langle R\rangle_{\tilde{P}}=-2 \mu+\tau, \quad \tau=\frac{\left\langle y_{0}\right| T_{0}^{T}+T_{0}\left|y_{0}\right\rangle}{\left\langle y_{0} \mid y_{0}\right\rangle}
$$

## Transient behaviour generators

- Propose a fixed $T_{0}$ model:

$$
\tilde{P}\left(X ; T_{0}\right)[d X] \sim \delta\left(T-T_{0}\right) P(X)[d X]
$$

- Seems artificial but has two properties:
(1) Does not spoil stability (eigenvalues stay in place)
(2) Does modify reactivity (transient regime!)
- $T_{0}$ resembles an external field:

$$
\langle R\rangle_{\tilde{P}}=-2 \mu+\tau, \quad \tau=\frac{\left\langle y_{0}\right| T_{0}^{T}+T_{0}\left|y_{0}\right\rangle}{\left\langle y_{0} \mid y_{0}\right\rangle}
$$

- ...or a (not so distant) echo of eigenvectors


## Transient behaviour generators

- Phase space is now two-dimensional with proper transient regime:



## Recap and Future

## Recap:

- Transient behaviour is an early time phenomenon abundant in real-life systems
- May-Wigner model contains a regime of parameters where transient dynamics is present although rare
- Transient trajectories are generated by eigenvector degrees of freedom


## Recap and Future

## Recap:

- Transient behaviour is an early time phenomenon abundant in real-life systems
- May-Wigner model contains a regime of parameters where transient dynamics is present although rare
- Transient trajectories are generated by eigenvector degrees of freedom


## Future:

- Reactivity is not an exact measure of transient behaviour
- What about $t_{\text {max }}$ ? or amplification?
- Statistics of the norm $|y(t)|^{2}$ (variance and beyond)
- Echoes of transient behaviour in the chaotic phase


[^0]:    $\dagger$ All entries are in units of $\mathrm{yr}^{-1}$.

